

Math 3230 - Abstract Algebra I

Summary of terms and theorems

1 Binary operations

Definitions and Theorems

1. *Associativity* of a binary operation \circ on a set A means $(a \circ b) \circ c = a \circ (b \circ c)$ for **all** $a, b, c \in A$.
2. *Commutativity* of a binary operation \circ on a set A means $a \circ b = b \circ a$ for **all** $a, b \in A$.
3. An *identity* element for a binary operation \circ on a set A is an $e \in A$ such that $e \circ a = a$ and $a \circ e = a$ for **all** $a \in A$.
4. If the binary operation \circ on A has identity e , an *inverse* of $a \in A$ is $a' \in A$ such that $a \circ a' = e$ and $a' \circ a = e$. **Note:** the inverse is in A and depends on the particular element. If there is no identity element, inverses make no sense.

Examples

1. In \mathbb{R} , addition and multiplication are both associative and commutative, with respective identities 0 and 1: for all a, b , and c in \mathbb{R} ,

$$\begin{aligned}(a + b) + c &= a + (b + c) & (ab)c &= a(bc) \\ a + b &= b + a & ab &= ba \\ a + 0 &= 0 + a = a & a \cdot 1 &= 1 \cdot a = a.\end{aligned}$$

In \mathbb{R} the additive inverse of a is $-a$, and for nonzero a in \mathbb{R} its multiplicative inverse is $1/a$ (0 has no multiplicative inverse).

2. In \mathbb{C} addition and multiplication are both associative and commutative, with respective identities 0 and 1 (formulas in the previous example remain valid with real numbers replaced by complex numbers). In \mathbb{C} the additive inverse of $z = x + yi$ is $-x - yi$, and for nonzero $z = x + yi$ in \mathbb{C} its multiplicative inverse is $(x - yi)/(x^2 + y^2)$.
3. Matrix multiplication on $M_n(\mathbb{R})$ is associative with identity I_n . It is **not** commutative when $n \geq 2$. A matrix in $M_n(\mathbb{R})$ has an inverse for multiplication precisely when its determinant is not 0. In the 2×2 case, the inverse of $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is $\frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$ when $ad - bc \neq 0$.
4. For any set X , composition of functions $X \rightarrow X$ is associative: if $f: X \rightarrow X$, $g: X \rightarrow X$, and $h: X \rightarrow X$ are all functions then $(f \circ g) \circ h = f \circ (g \circ h)$ as functions $X \rightarrow X$. Composition is usually not commutative: for most pairs of functions $X \rightarrow X$ the order of composition matters. The identity function $i: X \rightarrow X$ for composition is $i(x) = x$ for all $x \in X$. A function $f: X \rightarrow X$ has an inverse for composition precisely when it is a bijection (injective and surjective).

5. For any set X , the functions $X \rightarrow \mathbb{R}$ (not to be confused with the functions $X \rightarrow X$ in the previous example) can be added or multiplied pointwise: if $f: X \rightarrow \mathbb{R}$ and $g: X \rightarrow \mathbb{R}$ then we define $f + g: X \rightarrow \mathbb{R}$ and $fg: X \rightarrow \mathbb{R}$ by $(f + g)(x) = f(x) + g(x)$ and $(fg)(x) = f(x)g(x)$ for $x \in X$. Both addition and multiplication of functions $X \rightarrow \mathbb{R}$ are commutative and associative. For functions $X \rightarrow \mathbb{R}$ the identity for addition is the constant function 0 and the identity for multiplication is the constant function 1. Every function $f: X \rightarrow \mathbb{R}$ has additive inverse $-f$, where $(-f)(x) = -(f(x))$ for all $x \in X$, and f has a multiplicative inverse precisely when it never takes the value 0, in which case its multiplicative inverse is the function $g(x) = 1/f(x)$ for all $x \in X$.

Nonexamples

Because associativity and commutativity are properties on all pairs in a set, to prove a binary operation is not associative or not commutative it suffices to find a single counterexample: the property might hold some of the time but it has to fail at least once.

1. Subtraction on \mathbb{Z} is not associative or commutative: $1 - (2 - 3) = 2$ while $(1 - 2) - 3 = -4$ and $1 - 2 = -1$ while $2 - 1 = 1$. There is no identity element for subtraction: if $e \in \mathbb{Z}$ satisfies $e - a = a$ for all a in \mathbb{Z} then at $a = 0$ we see $e - 0 = 0$, so $e = 0$ and then $0 - a = a$ for all $a \in \mathbb{Z}$, which is false nearly all the time (indeed for every nonzero a).
2. Division on $\mathbb{R} - \{0\}$ is not associative or commutative: $1/(2/3) = 3/2$ while $(1/2)/3 = 1/6$ and $1/2 \neq 2/1$. There is no identity element either (why?).
3. On $\mathbb{R}_{>0}$, exponentiation ($a \circ b = a^b$) is not associative or commutative. For example, $(2^1)^2 = 4$ and $2^{(1^2)} = 2$, while $2^1 = 2$ and $1^2 = 1$.
4. Addition on $\mathbb{R}_{>0}$ is associative and commutative, but there is no identity.
5. Addition on $\mathbb{R}_{\geq 0}$ is associative and commutative with identity 0, but there are no inverses for nonzero elements: if $a \in \mathbb{R}_{\geq 0}$ and $a \neq 0$, there is no $a' \in \mathbb{R}_{\geq 0}$ such that $a + a' = 0$.

2 Groups

Definitions and Theorems

1. A *group* is a set G with a binary operation \circ on it that is associative, has an identity (in $G!$), and each element of G has an inverse (in $G!$). For a general group G its operation is usually written multiplicatively: $g \circ h$ is written as gh , $\underbrace{g \circ g \circ \cdots \circ g}_{n \text{ times}}$ is written as g^n , and the inverse of g is written as g^{-1} .
2. When the operation on a group G is commutative, the group is called *commutative* or *abelian*. In an abstract abelian group additive notation is often used: the identity is 0, the operation is $g+h$, $\underbrace{g \circ g \circ \cdots \circ g}_{n \text{ times}}$ is written as ng , and the inverse of g is written as $-g$. (Do not use additive notation if a group is not abelian.)
3. Groups that are not commutative are called *noncommutative* or *nonabelian*. Noncommutativity means $gh \neq hg$ at least once, not always (e.g., $ge = eg$ for all g in a group).
4. A group G is called *cyclic* if there is some element $g \in G$ such that (using multiplicative notation) every element of G has the form g^n for $n \in \mathbb{Z}$. We then write $G = \langle g \rangle = \{\dots, g^{-2}, g^{-1}, e, g, g^2, \dots\}$ and say g is a *generator* of G . Cyclic groups must be abelian, but the converse is false (see Nonexamples below).

Note. For groups where the operation is written additively, we write ng for n copies of g added together instead of g^n (n copies of g multiplied together), so $\langle g \rangle = \{ng : n \in \mathbb{Z}\} = \{\dots, -2g, -g, 0, g, 2g, \dots\}$.

Examples

1. The sets \mathbb{Z} , \mathbb{Q} , \mathbb{R} , and \mathbb{C} with the operation of addition are abelian groups. Other abelian groups are the set of n -tuples \mathbb{Z}^n , \mathbb{Q}^n , \mathbb{R}^n , and \mathbb{C}^n using componentwise addition and the set of $n \times n$ matrices $M_n(\mathbb{Z})$, $M_n(\mathbb{Q})$, $M_n(\mathbb{R})$ and $M_n(\mathbb{C})$ with matrix addition.
2. Three groups under multiplication are \mathbb{Q}^\times , \mathbb{R}^\times , and \mathbb{C}^\times , which are the nonzero rational numbers, nonzero real numbers, and nonzero complex numbers.
3. The set \mathbb{Z}_m with the operation of addition modulo m is a finite abelian group.
4. The set μ_m of m th roots of unity in \mathbb{C} with the operation of multiplication is a finite abelian group.
5. The set $U(m)$ of integers modulo m that are relatively prime to m , with the operation of multiplication modulo m , is a finite abelian group.
6. The set of $n \times n$ real matrices with nonzero determinant is a nonabelian group under multiplication. This group is denoted $\text{GL}_n(\mathbb{R})$.

7. Some finite nonabelian groups include S_n (all permutations of $\{1, 2, \dots, n\}$) for $n \geq 3$ and D_n (all rigid motions of a regular n -gon) for $n \geq 3$, both under the operation of composition. In S_n every pair of disjoint permutations commute, but non-disjoint permutations may or may not commute: in S_3 , (12) and (13) don't commute while (123) and (132) do commute (they are inverses).
8. The group \mathbb{Z} is cyclic, with generator 1 or -1 .
9. The group \mathbb{Z}_m is cyclic, with generator $1 \bmod m$ or more generally $a \bmod m$ when $(a, m) = 1$. For instance, additive generators of \mathbb{Z}_8 are 1, 3, 5, or $7 \bmod 8$.
10. The group μ_m is cyclic, with a generator $\cos(2\pi/m) + i \sin(2\pi/m)$.

Nonexamples

1. The sets \mathbb{Z} , \mathbb{Q} , \mathbb{R} , \mathbb{C} , and \mathbb{Z}_m under multiplication are not groups since 0 has no inverse.
2. The nonzero integers $\mathbb{Z} - \{0\}$ under multiplication are not a group since most integers (in fact all of them except ± 1) have no inverse for multiplication in $\mathbb{Z} - \{0\}$.
3. The set of 2×2 *integer* matrices with nonzero determinant is not a group under multiplication because some (in fact most) such matrices don't have a matrix inverse with integer entries.
4. The group \mathbb{Q} under addition is not cyclic: no fraction has all its (additive) multiples equal to all of \mathbb{Q} .
5. Every cyclic group is abelian but many abelian groups are not cyclic. For instance, all $U(m)$ are abelian and many are not cyclic; the first three noncyclic $U(m)$ are $U(8)$, $U(12)$, and $U(15)$.

3 Subgroups

Definitions and Theorems

1. A *subgroup* of a group G is a subset H of G that is a group using the same operation that G has. (Associativity on a subset is automatic, and if G is an abelian group then commutativity of the operation on a subset is automatic. The identity element and inverses in a subgroup have to be the same as in G .)
2. A *cyclic subgroup* H is a subgroup that is a cyclic group in its own right: $H = \langle a \rangle = \{a^n : n \in \mathbb{Z}\}$ for some $a \in H$.
3. An *abelian subgroup* H is a subgroup that is an abelian group in its own right: $hk = kh$ for all $h, k \in H$.
4. The *center* $Z(G)$ of a group G is all elements of G that commute with everything in G : $Z(G) = \{z \in G : zg = gz \text{ for all } g \in G\}$.
5. **Theorem.** *Every subgroup of an abelian group is abelian and every subgroup of a cyclic group is cyclic.* The first result only relies on some very simple reasoning (and knowing what the words mean), but the second result requires a clever idea (using division algorithm in \mathbb{Z}).

Examples

1. In S_4 , (12) and (34) commute and $H = \{(1), (12), (34), (12)(34)\}$ is an abelian subgroup of S_4 that is not cyclic (every element squares to (1)).
2. In S_4 let $g = (1234)$. Then $g^2 = (13)(24)$, $g^3 = (1432) = (4321)$, and $g^4 = (1)$, so $\langle g \rangle = \{(1), (1234), (13)(24), (4321)\}$.
3. Subgroups of \mathbb{Z} include the even integers $2\mathbb{Z} = \{2m : m \in \mathbb{Z}\}$, and more generally $a\mathbb{Z} = \{am : m \in \mathbb{Z}\}$ for $a \in \mathbb{Z}$. (In fact it is a theorem that every subgroup of \mathbb{Z} is $a\mathbb{Z}$ for some integer a .)
4. In \mathbb{R}^\times , the subset $\mathbb{R}_{>0}$ of positive numbers is a subgroup.
5. In \mathbb{R}^\times , the subset $\langle 2 \rangle = \{2^n : n \in \mathbb{Z}\} = \{\dots, 1/4, 1/2, 1, 2, 4, \dots\}$ is a subgroup.
6. In \mathbb{C}^\times , the subset $S^1 = \{z \in \mathbb{C} : |z| = 1\}$ is a subgroup.
7. In $\text{GL}_2(\mathbb{R})$, one cyclic subgroup is $\{(\begin{smallmatrix} 1 & n \\ 0 & 1 \end{smallmatrix}) : n \in \mathbb{Z}\} = \{(\begin{smallmatrix} 1 & 1 \\ 0 & 1 \end{smallmatrix})^n : n \in \mathbb{Z}\} = \langle (\begin{smallmatrix} 1 & 1 \\ 0 & 1 \end{smallmatrix}) \rangle$.
8. Subgroups of $\text{GL}_2(\mathbb{R})$ include $\text{Aff}(\mathbb{R}) = \{(\begin{smallmatrix} a & b \\ 0 & 1 \end{smallmatrix}) : a \in \mathbb{R}^\times, b \in \mathbb{R}\}$ and $\text{SL}_2(\mathbb{R}) =$ the 2×2 matrices with determinant 1. These are both nonabelian, but the subgroup of diagonal matrices $(\begin{smallmatrix} a & 0 \\ 0 & d \end{smallmatrix})$ where $a, d \in \mathbb{R}^\times$ is an abelian subgroup.
9. The alternating group A_n , which is all *even* permutations in S_n , is a subgroup of S_n .
10. Every group G has the subgroups G and $\{e\}$. If a subgroup contains a then it must at least contain $\langle a \rangle$, but could be larger.

11. The group S_n is not cyclic for $n \geq 3$ since it is nonabelian for $n \geq 3$. While S_n for $n \geq 3$ does not have a single generator, it is generated by all the transpositions (ij) .
12. The center of a group is a subgroup of G . If G is abelian then $Z(G) = G$, and conversely. Having $Z(G)$ be a “small” subgroup of G is a measure of G being highly nonabelian.
13. The center of $\text{GL}_2(\mathbb{R})$ is the scalar diagonal matrices $\left\{ \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} : a \in \mathbb{R}^\times \right\}$.

Nonexamples

1. In \mathbb{Z} , while the even integers $2\mathbb{Z}$ are a subgroup, the odd integers $1 + 2\mathbb{Z}$ are not a subgroup (no identity, not closed under addition).
2. In \mathbb{R}^\times , while the positive numbers $\mathbb{R}_{>0}$ are a subgroup, the negative numbers $\mathbb{R}_{<0}$ are not a subgroup (no identity, not closed under multiplication).
3. Even though \mathbb{R}^\times is a subset of \mathbb{R} and each is a group under a suitable operation (addition for \mathbb{R} , multiplication for \mathbb{R}^\times), we do not consider \mathbb{R}^\times to be a subgroup of \mathbb{R} since the operations are not the same.
4. In the group \mathbb{R} , the subset of positive real numbers is closed under addition but is not a subgroup of \mathbb{R} since there is no additive identity. The subset $\mathbb{R}_{\geq 0}$ of nonnegative numbers is not a group (under addition) even though it has an identity since additive inverses generally fail to exist in $\mathbb{R}_{\geq 0}$.

4 Order

Definitions and Theorems

1. The *order* of a subgroup $H \subset G$ is the size of H and is denoted $|H|$. When H is infinite, often we write $|H| = \infty$.
2. The *order* of an element $g \in G$ is the size of $\langle g \rangle$ and is denoted $|g|$, so $|g| = |\langle g \rangle|$.
3. **Theorem.** *If $|g| < \infty$ then $|g|$ is the smallest $n \geq 1$ such that $g^n = e$. If $|g| = \infty$ there is no $n \geq 1$ such that $g^n = e$.*
4. **Theorem.** *If $|g| = n$ is finite then $\langle g \rangle = \{1, g, \dots, g^{n-1}\}$ and $g^i = g^j \iff i \equiv j \pmod n$. We have $|g^k| = n$ when $(k, n) = 1$ and $|g^d| = n/d$ if $d \mid n$.*

Examples

1. We have $|\mathbb{Z}_m| = m$, $|S_n| = n!$, $|A_n| = n!/2$, and $|D_n| = 2n$. The order of $U(m)$ is denoted $\varphi(m)$, so $\varphi(4) = |\{1, 3 \pmod 4\}| = 2$ and $\varphi(5) = |\{1, 2, 3, 4 \pmod 5\}| = 4$.
2. In \mathbb{Z} , every integer besides 0 has infinite order under addition, while 0 has order 1.
3. In the group \mathbb{R}^\times , 1 has order 1, -1 has order 2 (because $(-1)^2 = 1$ while $(-1)^1 \neq 1$), and every nonzero real number besides ± 1 has infinite order.
4. In \mathbb{C}^\times , -1 has order 2 and i has order 4. The complex number $\cos(2\pi/n) + i \sin(2\pi/n)$ has order n . Most nonzero complex numbers, like most nonzero real numbers, have infinite multiplicative order.
5. In S_4 , $|(1234)| = 4$: $(1234)^2 = (13)(24)$, $(1234)^3 = (1432) = (4321)$, and $(1234)^4 = (1)$. More generally, in S_n a k -cycle $(i_1 i_2 \dots i_k)$ has order k .
6. In a finite group every element has finite order. In \mathbb{Z}_m the order of $a \pmod m$ is $m/(a, m)$. In $U(m)$ there is no simple formula for the order of an element (other than $\pm 1 \pmod m$).

Nonexamples

1. If $g^n = e$ in a group, this does **not** imply $|g| = n$. Consider $(-1)^4 = 1$ in \mathbb{R}^\times and -1 has order 2, not 4. What $g^n = e$ implies is that $|g| \leq n$. In fact, $g^n = e \iff |g| \mid n$.
2. In S_3 , $|(12)| = |(23)| = 2$ and $|(12)(23)| = |(123)| = 3$, so $|(12)(23)| \neq |(12)|||(23)|$.
3. In $\text{GL}_2(\mathbb{R})$, $\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$ and $\begin{pmatrix} -1 & -1 \\ 0 & 1 \end{pmatrix}$ both have order 2, but their product $\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & -1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ has infinite order (for $n \in \mathbb{Z}$, $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}^n = \begin{pmatrix} 1 & n \\ 0 & 1 \end{pmatrix}$), so in some groups two noncommuting (!) elements with finite order can have a product with infinite order.

5 Cosets

Definitions and Theorems

1. For a subgroup H in a group G , a *left coset* of H is a subset of the form $gH = \{gh : h \in H\}$ and a *right coset* of H is a subset of the form $Hg = \{hg : h \in H\}$. A coset is usually not a subgroup but can be viewed as a “translated subgroup” from either the left side or right side. When G is nonabelian, gH need not equal Hg as subsets of G .

Additive notation: a left coset is $g + H = \{g + h : h \in H\}$ and a right coset is $H + g = \{h + g : h \in H\}$. Since $+$ is commutative we have $g + h = h + g$ for all $h \in H$, so $g + H = H + g$ as subsets of G .

2. A *representative* of a coset (gH or Hg) is any element in the coset.

Examples

1. In \mathbb{Z} , $3 + 2\mathbb{Z} = 1 + 2\mathbb{Z}$ and this is not a subgroup of \mathbb{Z} .
2. In \mathbb{Z} , $1 + 2\mathbb{Z} = 3 + 2\mathbb{Z} = 5 + 2\mathbb{Z} = -1 + 2\mathbb{Z} = a + 2\mathbb{Z}$ for each odd integer a (that is, each a in the coset $1 + 2\mathbb{Z}$).
3. In S_4 , let $H = \langle(1234)\rangle = \{(1234), (13)(24), (1432), (1)\}$. Then

$$\begin{aligned}(12)H &= \{(234), (1324), (143), (12)\} \\ H(12) &= \{(134), (1423), (243), (12)\}\end{aligned}$$

and

$$\begin{aligned}(13)H &= \{(12)(34), (24), (14)(23), (13)\} \\ H(13) &= \{(14)(23), (24), (12)(34), (13)\}.\end{aligned}$$

Thus $(12)H \neq H(12)$ while $(13)H = H(13)$.

4. In D_4 let $H = \langle s \rangle = \{1, s\}$. Then $rH = \{r, rs\}$ and $Hr = \{r, sr\}$. Since $rs \neq sr$ in D_4 , the left and right cosets rH and Hr are different (their intersection is $\{r\}$).
5. In D_4 , let $H = \langle s \rangle = \{1, s\}$. Then $rsH = \{rs, rs^2\} = \{rs, r\} = rH$ (see previous example). Both r and rs are in this coset and they represent the same left H -coset.

Nonexamples

1. In S_4 let H be the subgroup $\{(1), (12), (34), (12)(34)\}$. For $g = (1234)$ we have

$$\begin{aligned}gH &= \{(1234), (134), (123), (13)\}, \\ Hg &= \{(1234), (234), (124), (24)\}\end{aligned}$$

so $gH \neq Hg$.

6 Dihedral Groups (review)

Definitions and Theorems

1. For $n \geq 3$, the group D_n is $\{1, r, r^2, \dots, r^{n-1}, s, rs, r^2s, \dots, r^{n-1}s\}$ where r has order n , s has order 2, and $sr = r^{-1}s$. The order of this group is $2n$.
2. **Theorem.** For all $k \in \mathbb{Z}$, $sr^k = r^{-k}s$.
3. **Theorem.** The center of D_n is $\{1\}$ if n is odd and $\{1, r^{n/2}\}$ if n is even.

Examples

1. In D_4 , $rsr^2s^3r^3s = rsr^2sr^3s = rr^{-2}ssr^3s = r^{-1}r^3s = r^2s$.
2. In D_n , the reflections are $s, rs, \dots, r^{n-1}s$ and all have order 2. In particular, rs has order 2, so $|rs| = 2$ while $|r||s| = n \cdot 2 = 2n$. Thus $|rs| \neq |r||s|$.
3. The only rotation of order 2 is $r^{n/2}$ (180-degree rotation) for even n .

7 Index and Lagrange's Theorem

Definitions and Theorems

- Theorem.** *If H is a subgroup of a group G then different left cosets of H are disjoint. Equivalently, if $gH \cap g'H \neq \emptyset$ then $gH = g'H$. In particular, if $g' \in gH$ then $g'H = gH$. Each left coset gH has the same cardinality as H : $H \rightarrow gH$ by $h \mapsto gh$ is a bijection between H and gH . Similar results hold for right cosets: if $Hg \cap Hg' \neq \emptyset$ then $Hg = Hg'$, and $H \rightarrow Hg$ by $h \mapsto hg$ is a bijection between H and Hg .*
- The *index* of a subgroup H in G is the number of different left cosets of H in G . This is also the number of different right cosets of H in G . It is denoted $[G : H]$.
- Theorem.** (Lagrange) *If H is a subgroup of a finite group G then $[G : H] \cdot |H| = |G|$. In particular, in a finite group each subgroup has order dividing the order of the group.*
- Theorem.** *The order of each element of a finite group G divides the order of G . In particular, $g^{|G|} = e$ for all $g \in G$. (For abelian G this can be proved without using Lagrange's theorem.)*
- Theorem.** (Fermat) *For prime p , if $a \not\equiv 0 \pmod{p}$ then $a^{p-1} \equiv 1 \pmod{p}$. This is the special case of Theorem 4 for $G = U(p)$.*
- Theorem.** (Euler) *For $m \geq 2$, if $(a, m) = 1$ then $a^{\varphi(m)} \equiv 1 \pmod{m}$. This is the special case Theorem 4 for $G = U(m)$.*

Examples

- For a subgroup H of a finite group G , $[G : H] = |G|/|H|$.
- $[\mathbb{Z} : m\mathbb{Z}] = |\{m\mathbb{Z}, 1 + m\mathbb{Z}, \dots, m - 1 + m\mathbb{Z}\}| = m$ for each positive integer m .
- $[\mathbb{R}^\times : \mathbb{R}_{>0}] = 2$ since $\mathbb{R}^\times = \mathbb{R}_{>0} \cup -\mathbb{R}_{>0}$ (cosets are positive and negative real numbers).
- $[\mathbb{R}^\times : \{\pm 1\}] = \infty$ since each coset is of the form $x\{\pm 1\} = \{x, -x\}$, a pair of numbers equal up to sign, and there are infinitely many such cosets in \mathbb{R}^\times .
- $[\mathbb{R} : \mathbb{Z}] = \infty$: the different cosets $a + \mathbb{Z}$ are represented by the real numbers a in the interval $[0, 1)$.

8 Conjugation

Definitions and Theorems

1. In a group G , we call elements x and y *conjugate* if $y = gxg^{-1}$ for some $g \in G$.
2. The *conjugacy class* of $x \in G$ is $\{gxg^{-1} : g \in G\}$.
3. In a group G , we call subgroups H and K *conjugate* if $K = gHg^{-1} = \{ghg^{-1} : h \in H\}$ for some $g \in G$.
4. **Theorem.** *Different conjugacy classes in a group are disjoint. Equivalently, if two conjugacy classes in a group overlap then they are equal.*
5. **Theorem.** *If H is a subgroup of G then gHg^{-1} is also a subgroup of G for each $g \in G$. (This is a contrast with cosets gH of H , which are **never** subgroups except for the coset H itself.)*
6. **Theorem.** *For $g \in G$ and a subgroup H of G , the conditions $gH = Hg$ and $gHg^{-1} = H$ are equivalent.*
7. **Theorem.** *For a subgroup H of G , $gHg^{-1} = H$ for all $g \in G$ if and only if $gHg^{-1} \subset H$ for all $g \in G$.*

Examples

1. In D_4 , the conjugacy classes are $\{1\}$, $\{r^2\}$, $\{r, r^3\}$, $\{s, r^2s\}$, $\{rs, r^3s\}$.
2. In D_n , all reflections are conjugate when n is odd (each reflection is across a line through a vertex and the center of the opposite edge) and there are two conjugacy classes of reflections when n is even (reflection across a vertex-vertex line vs. across a vertex-opposite edge line).
3. In S_n , all transpositions are conjugate to (12) : if $i \neq 1, 2$ and $j \neq 1, 2$ then

$$(ij) = (1i)(2j)(12)(2j)(1i) = (1i)(2j)(12)((1i)(2j))^{-1}.$$

If $i = 1$ and $j \neq 1, 2$ then $(ij) = (1j) = (2j)(12)(2j) = (2j)(12)(2j)^{-1}$. If $i = 2$ and $j \neq 1, 2$ then $(ij) = (2j) = (1j)(12)(1j) = (1j)(12)(1j)^{-1}$.

4. For a k -cycle $(i_1 i_2 \dots i_k)$ and $\sigma \in S_n$, $\sigma(i_1 i_2 \dots i_k)\sigma^{-1} = (\sigma(i_1) \sigma(i_2) \dots \sigma(i_k))$ is also a k -cycle. This explains the previous example: if $i \neq 1, 2$ and $j \neq 1, 2$ then $(ij) = \sigma(12)\sigma^{-1}$ where $\sigma = \begin{pmatrix} 12ij \\ ij12 \end{pmatrix}$, if $i = 1$ and $j \neq 1, 2$ then $(ij) = (1j) = \sigma(12)\sigma^{-1}$ where $\sigma = \begin{pmatrix} 2j \\ j2 \end{pmatrix} = (2j)$, and if $i = 2$ and $j \neq 1, 2$ then $(ij) = (2j) = \sigma(12)\sigma^{-1} = \sigma(21)\sigma^{-1}$, where $\sigma = \begin{pmatrix} 1j \\ j1 \end{pmatrix} = (1j)$.
5. In S_4 let H be the subgroup $\{(1), (12), (34), (12)(34)\}$. For $g = (1234)$ we have $g^{-1} = (4321)$ and

$$\begin{aligned} (1234)(1)(4321) &= (1) & (1234)(12)(4321) &= (23) \\ (1234)(34)(4321) &= (14) & (1234)(12)(34)(4321) &= (14)(23), \end{aligned}$$

so

$$gHg^{-1} = \{(1), (14), (23), (14)(23)\} \neq H.$$

Nonexamples

1. The rotations r and r^3 in D_4 are conjugate in D_4 : $sr s^{-1} = r^3$. But r and r^3 are **not** conjugate in the subgroup $\langle r \rangle$ since this subgroup is abelian and different elements of an abelian group are not conjugate in that group.
2. Since $|gHg^{-1}| = |H|$ when H is finite, to prove $gHg^{-1} = H$ for a specific $g \in G$ it suffices to show $gHg^{-1} \subset H$ (that is, $ghg^{-1} \in H$ for all $h \in H$). But there are infinite subgroups $H \subset G$ where, for specific $g \in G$, $gHg^{-1} \subset H$ and $gHg^{-1} \neq H$. For example, let $G = \text{Aff}(\mathbb{R}) = \left\{ \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix} : a \in \mathbb{R}^\times, b \in \mathbb{R} \right\}$ and $H = \left\langle \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \right\rangle = \left\{ \begin{pmatrix} 1 & n \\ 0 & 1 \end{pmatrix} : n \in \mathbb{Z} \right\}$. If $g = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$ then $g^{-1} = \begin{pmatrix} 1/2 & 0 \\ 0 & 1 \end{pmatrix}$ and $g \begin{pmatrix} 1 & n \\ 0 & 1 \end{pmatrix} g^{-1} = \begin{pmatrix} 1 & 2n \\ 0 & 1 \end{pmatrix}$, so $gHg^{-1} = \left\{ \begin{pmatrix} 1 & 2n \\ 0 & 1 \end{pmatrix} : n \in \mathbb{Z} \right\}$ is a proper subset of H (it does not contain $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$). Moreover, $g^{-1} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} g^{-1} = \begin{pmatrix} 1 & 1/2 \\ 0 & 1 \end{pmatrix} \notin H$, so in this example we have $gHg^{-1} \subset H$ and $g^{-1}Hg \not\subset H$!

9 Normal subgroups, quotient groups

Definitions and Theorems

1. A subgroup N in a group G is called *normal* if its left and right coset by each $g \in G$ is the same: $gN = Ng$ for all $g \in G$. (**Warning:** saying $gN = Ng$ means the two sets gN and Ng are equal, **not** necessarily that $gn = ng$ for all $n \in N$.) The notation for N being a normal subgroup of G is $N \triangleleft G$ and we often write gN as \bar{g} .
2. **Theorem.** *Every subgroup of a group with index 2 is a normal subgroup.*
3. $[S_n : A_n] = 2$ and therefore A_n is a normal subgroup of S_n since it has index 2.
4. If N is a normal subgroup of G then its cosets can be multiplied by the rule $gN \cdot g'N = gg'N$ (or $\bar{g} \cdot \bar{g}' = \overline{gg'}$). This is well-defined (that is, independent of the representatives used for the two cosets of N) and makes the cosets of N in G into a group called the *quotient group* or *factor group* of G modulo N , and denoted G/N . Its order is $[G : N]$, the identity is $\bar{1} = N$, and $(gN)^{-1} = g^{-1}N$ (that is, $\bar{g}^{-1} = \overline{g^{-1}}$).
5. **Theorem.** *Let $N \triangleleft G$. If G is abelian then G/N is abelian. If G is cyclic then G/N is cyclic.*

Examples

1. In a group G , the center $Z(G)$ is a normal subgroup.
2. In an abelian group every subgroup is normal. The converse is false: every subgroup of Q_8 is normal but Q_8 is not abelian.
3. In \mathbb{R} , $2\pi\mathbb{Z}$ is a subgroup that is automatically normal since \mathbb{R} is abelian, and the quotient group $\mathbb{R}/2\pi\mathbb{Z}$ has coset representatives $a \in [0, 2\pi)$. Cosets in $\mathbb{R}/2\pi\mathbb{Z}$ look like angles on a circle using radian measure, *e.g.*, $-\pi = \pi$ in $\mathbb{R}/2\pi\mathbb{Z}$ just as $-\pi$ and π are the same angle in radians. The real numbers equal to $\bar{0}$ in $\mathbb{R}/2\pi\mathbb{Z}$ are the integral multiples of 2π . Addition in the quotient group $\mathbb{R}/2\pi\mathbb{Z}$ is the same as adding angles up to an integral multiple of 2π .
4. The center of D_4 is $N = \{1, r^2\}$. What “is” the group D_4/N ? It has order 4. Is it abelian? Is it cyclic? Writing out the cosets (left vs. right doesn’t matter since $N \triangleleft D_4$), we get

$$\bar{1} = N = \{1, r^2\}, \quad \bar{r} = rN = \{r, r^3\},$$

$$\bar{s} = sN = \{s, sr^2\} = \{s, r^2s\}, \quad \bar{rs} = rsN = \{rs, rsr^2\} = \{rs, r^3s\}.$$

These are disjoint and fill up all of D_4 , so we are done with the listing of cosets. The identity in D_4/N is $\bar{1} = N$.

In the group D_4/N , $\bar{r}^2 = \overline{r^2} = \bar{1}$ since $r^2 \in N$. (More explicitly in terms of cosets, $(rN)^2 = rNrN = r^2N = N$ since $r^2 \in N$.) Thus \bar{r} has order 2 in D_4/N even though r has order 4 in D_4 (a certain amount of collapsing has happened). Also $\bar{s}^2 = \overline{s^2} = \bar{1}$ and $\overline{rs^2} = \overline{(rs)^2} = \bar{1}$.

since $(rs)^2 = 1$ (check that algebraically, or see that rs is a reflection). Thus each non-identity element of D_4/N has order 2, so D_4/N (having order 4) is not cyclic. Writing $D_4/N = \{\bar{1}, \bar{r}, \bar{s}, \bar{rs}\}$, we have $\bar{r} \cdot \bar{s} = \bar{s} \cdot \bar{r}$ since the left side is $\bar{rs} = rsN$ and the right side is $\bar{sr} = srN = r^3sN = rsN$ (the N -coset containing r^3s is rsN), so D_4/N is abelian even though D_4 is not.

5. In S_4 let N be the subgroup $\{(1), (12)(34), (13)(24), (14)(23)\}$ (identity and all products of disjoint 2-cycles). For $g = (1234)$ we have

$$\begin{aligned} gN &= \{(1234), (13), (1432), (24)\} \\ Ng &= \{(1234), (24), (1432), (13)\}, \end{aligned}$$

so $gN = Ng$ for this one g . To prove $gN = Ng$ for **all** $g \in S_4$ it suffices to check that equation for a set of permutations that generates S_4 , such as (12) , (23) , and (34) . Check that $(12)N = N(12)$, $(23)N = N(23)$, and $(34)N = N(34)$.

6. In the group S_4 the subgroup $N = \{(1), (12)(34), (13)(24), (14)(23)\}$ is normal (see the previous result). The number of cosets of N in S_4 is $[S_4 : N] = |S_4|/|N| = 24/4 = 6$. The 6 cosets

$$(1)N, \quad (12)N, \quad (13)N, \quad (23)N, \quad (123)N, \quad (321)N$$

are distinct, either by tedious direct calculation or by the following conceptual reasoning: if $aN = bN$ for a, b taken from $\{(1), (12), (13), (23), (123), (132)\}$ then $ab^{-1} \in N$, and the chosen representatives belong to S_3 , so $ab^{-1} \in S_3 \cap N = \{(1)\}$, and thus $a = b$. Hence for different a and b in S_3 we have $aN \neq bN$. Therefore the above listing of 6 cosets, each of order $|N| = 4$, exhausts the group S_4 (of order $24 = 6 \cdot 4$).

Since $N \triangleleft S_4$, the group law in S_4/N is $(gN)(hN) = ghN$. From the choice of coset representatives above, the group law on S_4/N resembles the group law in S_3 .

In S_4 let H be the subgroup $\{(1), (12), (34), (12)(34)\}$. For $g = (1234)$ we have $gH \neq Hg$ since

$$\begin{aligned} gH &= \{(1234), (134), (123), (13)\}, \\ Hg &= \{(1234), (234), (124), (24)\} \end{aligned}$$

7. Let $G = S_4$ and let $H = \{(1), (12), (34), (12)(34)\}$. The operation $(aH)(bH) = abH$ is not well-defined on left H -cosets. That is, if $aH = a'H$ and $bH = b'H$, it is not always true that $abH = a'b'H$. Consider the left cosets

$$(13)H = \{(13), (123), (134), (1234)\}, \quad (14)H = \{(14), (124), (143), (1243)\}.$$

Then $(13)H = (134)H$ and $(14)H = (143)H$, but $(13)(14)H = (143)H = (14)H$ while $(134)(143)H = (1)H = H$. Since $H \neq (14)H$ (for example, $(14) \in (14)H$ but $(14) \notin H$), we get $(13)(14)H \neq (134)(143)H$.

Nonexamples

1. In D_4 , $\langle s \rangle = \{1, s\}$ is a subgroup of order 2 that is not normal since $r\langle s \rangle r^{-1} = \langle r s r^{-1} \rangle = \langle r^2 s \rangle = \{1, r^2 s\} \neq \langle s \rangle$. Also $\langle r^2 \rangle = \{1, r^2\}$ is a subgroup of order 2 that is normal (this is the center of D_4), so cyclic subgroups of a group with the same size need not both be normal or both be non-normal.

10 Homomorphisms

Definitions and Theorems

1. A *homomorphism* from the group (G, \cdot) to the group (H, \circ) is a function $f: G \rightarrow H$ that transforms the operation in G to the operation in H :

$$f(g_1 \cdot g_2) = f(g_1) \circ f(g_2)$$

for all $g_1, g_2 \in G$. The set $f(G) = \{f(g) : g \in G\}$ of all values f has in H is called the *image* of f .

2. The *kernel* of a homomorphism $f: G \rightarrow H$ is the elements in G mapped to the identity in H :

$$\ker f = \{g \in G : f(g) = e_H\}.$$

3. **Theorem.** *If $f: G \rightarrow H$ is a homomorphism then $f(e_G) = e_H$, $f(g)^n = f(g^n)$ for all $g \in G$ and $n \in \mathbb{Z}$, $\ker f$ is a subgroup of G , and image $f(G)$ is a subgroup of H .*

(If either group is written additively then the identities change: $f(0) = 0$ and $f(ng) = nf(g)$ if both groups are additive, $f(0) = 1$ and $f(ng) = f(g)^n$ if only the first group is additive, and $f(1) = 0$ and $f(g^n) = nf(g)$ if only the second group is additive.)

4. **Theorem.** *For every homomorphism $f: G \rightarrow H$ the kernel $\ker f$ is a normal subgroup of G .*
5. **Theorem.** *A homomorphism is injective if and only if its kernel is trivial.*
6. **Theorem.** *For a homomorphism $f: G \rightarrow H$ and $g \in G$ of order n , $f(g)$ has order dividing n .*
7. Let G be a group and N be a normal subgroup. Then there is a “canonical” reduction homomorphism $r: G \rightarrow G/N$ called *reduction mod N* , defined by $r(g) = gN = \bar{g}$ for all $g \in G$.

Examples

1. Doubling is a homomorphism $f: \mathbb{Z} \rightarrow \mathbb{Z}$ where $f(a) = 2a$ for all $a \in \mathbb{Z}$. Being a homomorphism means $2(a+b) = 2a+2b$, which is a special case of the distributive property for multiplication over addition. This homomorphism is injective but it is not surjective: its kernel is $\{0\}$ and its image is $2\mathbb{Z}$.
2. In an abelian group G , $(g_1g_2)^k = g_1^k g_2^k$ for all $g_1, g_2 \in G$ and $k \in \mathbb{Z}$, so for each integer k the k th power function $f(g) = g^k$ is a homomorphism $G \rightarrow G$. (If G is written additively the identity becomes $k(g_1 + g_2) = kg_1 + kg_2$. The previous example is the special case $G = \mathbb{Z}$ and $k = 2$, using additive notation.) If $k = -1$ the k th power homomorphism is inversion on G and this function is its own inverse since $(g^{-1})^{-1}$. For a nonabelian group, inversion $g \mapsto g^{-1}$ is *not* a homomorphism since $(gg')^{-1} = (g')^{-1}g^{-1}$, which usually is not $g^{-1}(g')^{-1}$.
3. For fixed $g \in G$, conjugation by g is the function $f: G \rightarrow G$ by $f(x) = gxg^{-1}$. This is an homomorphism from G to itself.

4. Reduction modulo 2 is a homomorphism $f: \mathbb{Z} \rightarrow \mathbb{Z}_2$, since $f(a+b) = a+b \bmod 2 = a \bmod 2 + b \bmod 2 = f(a) + f(b)$. This homomorphism is surjective but not injective. More generally, for each integer $m \geq 2$ the reduction $r: \mathbb{Z} \rightarrow \mathbb{Z}_m$ where $r(a) = a \bmod m$ is a homomorphism that is surjective but not injective.
5. For an $m \times n$ real matrix A , the function $L_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ where $L_A(\mathbf{v}) = A\mathbf{v}$ is additive, so it is a homomorphism (\mathbb{R}^n and \mathbb{R}^m are additive groups) and $\ker L_A = \{\mathbf{v} \in \mathbb{R}^n : A\mathbf{v} = \mathbf{0}\}$ is the null space of A .
6. If $N \triangleleft G$ then the reduction mapping $r: G \rightarrow G/N$ where $r(g) = gN$ is a homomorphism by the definition of the group operation in G/N and it is surjective with kernel N .
7. If $f: G \rightarrow \tilde{G}$ is a homomorphism and $N \triangleleft G$, the image $f(N)$ need not be a normal subgroup of \tilde{G} . For example, in D_3 if $G = \langle s \rangle = \{1, s\}$ and $\tilde{G} = D_3$, and $f: \langle s \rangle \rightarrow D_3$ is the inclusion function, then $\langle s \rangle \triangleleft \langle s \rangle$ but $f(\langle s \rangle) = \langle s \rangle \not\triangleleft D_3$.
8. The exponential function $\exp: \mathbb{R} \rightarrow \mathbb{R}_{>0}$ is a group homomorphism since $e^{x+y} = e^x e^y$, and the natural logarithm $\ln: \mathbb{R}_{>0} \rightarrow \mathbb{R}$ is a group homomorphism since $\ln(ab) = \ln a + \ln b$. That a homomorphism $f: G \rightarrow H$ satisfies $f(g^n) = f(g)^n$ is related to the equations $e^{nx} = (e^x)^n$ (homomorphism from an additive to multiplicative group) and $\ln(x^n) = n \ln x$ (homomorphism from a multiplicative to additive group).
9. The sign function $\text{sign}: \mathbb{R}^\times \rightarrow \{\pm 1\}$, sending each nonzero real number x to its sign, is a homomorphism that is surjective with kernel $\{x \in \mathbb{R}^\times : x > 0\} = \mathbb{R}_{>0}$.
10. Since $\det(AB) = \det A \det B$ for all A and B in $M_2(\mathbb{R})$, the determinant is a homomorphism $\det: \text{GL}_2(\mathbb{R}) \rightarrow \mathbb{R}^\times$ with kernel $\text{SL}_2(\mathbb{R})$ and image \mathbb{R}^\times since $a = \det\begin{pmatrix} a & 0 \\ 0 & 1 \end{pmatrix}$.

Nonexamples

1. The determinant is a multiplicative function $\det: M_2(\mathbb{R}) \rightarrow \mathbb{R}$, but this is not a homomorphism since $M_2(\mathbb{R})$ and \mathbb{R} are not groups under multiplication.
2. On a nonabelian group G , inversion $i: G \rightarrow G$ is **never** a homomorphism. We have $i(g_1 g_2) = (g_1 g_2)^{-1} = g_2^{-1} g_1^{-1} = i(g_2) i(g_1)$, so inversion actually reverses the order of multiplication. That is not a full proof of inversion not being a homomorphism. If inversion were a homomorphism then $i(g_1 g_2) = i(g_1) i(g_2) = g_1^{-1} g_2^{-1} = (g_2 g_1)^{-1}$ for all $g_1, g_2 \in G$, so we'd have $(g_1 g_2)^{-1} = (g_2 g_1)^{-1}$. Inverting both sides, $g_1 g_2 = g_2 g_1$ for all $g_1, g_2 \in G$, which means G is abelian, a contradiction.

11 Isomorphisms

Definitions and Theorems

1. An *isomorphism* from the group G to the group H is a bijective homomorphism $f: G \rightarrow H$. When there is an isomorphism from G to H we say G and H are *isomorphic* and write $G \cong H$.
2. **Theorem.** *Every infinite cyclic group is isomorphic to \mathbb{Z} .*
3. **Theorem.** *Every finite cyclic group of order n is isomorphic to \mathbb{Z}_n .*
4. **Theorem.** *If $f: G \rightarrow H$ is an isomorphism then it satisfies the following properties:*
 - g has order n if and only if $f(g)$ has order n ,
 - g and g' commute in G if and only if $f(g)$ and $f(g')$ commute in H ,
 - g and g' are conjugate in G if and only if $f(g)$ and $f(g')$ are conjugate in H ,
 - $f(Z(G)) = Z(H)$ (so $Z(G) \cong Z(H)$ using the isomorphism f from G to H),
 - G is abelian if and only if H is abelian, and G is cyclic if and only if H is cyclic.

All of these equivalences are in general *false* if $|G| > 1$ and $f: G \rightarrow \tilde{G}$ is the trivial homomorphism, which is not an isomorphism.

5. **First Isomorphism Theorem.** *If $f: G \rightarrow H$ is a homomorphism and $K = \ker f$, then G/K is isomorphic to the image $f(G)$ by the mapping $gK \mapsto f(g)$ for all $gK \in G/K$.*

In terms of the reduction homomorphism $r: G \rightarrow G/K$, there is a unique isomorphism $\bar{f}: G/K \rightarrow f(G)$ such that the diagram below commutes: $f = \bar{f} \circ r$.

$$\begin{array}{ccc}
 G & \xrightarrow{f} & H \\
 \searrow r & & \nearrow \bar{f} \\
 & G/K &
 \end{array}$$

(Note: A dashed arrow labeled \cong points from G/K to $f(G)$ in the original diagram.)

Examples

1. For fixed $g \in G$, conjugation by g is the function $f: G \rightarrow G$ by $f(x) = gxg^{-1}$. This is an isomorphism of G with itself.
2. When G is an *abelian* group, inversion $g \mapsto g^{-1}$ is an isomorphism of G with itself.
3. The exponential function $\exp: \mathbb{R} \rightarrow \mathbb{R}_{>0}$ and the logarithm $\ln: \mathbb{R}_{>0} \rightarrow \mathbb{R}$ are isomorphisms between \mathbb{R} and $\mathbb{R}_{>0}$, and are inverses of each others.
4. Since $\det: \text{GL}_2(\mathbb{R}) \rightarrow \mathbb{R}^\times$ is a homomorphism with kernel $\text{SL}_2(\mathbb{R})$ and image \mathbb{R}^\times , because $a = \det \begin{pmatrix} a & 0 \\ 0 & 1 \end{pmatrix}$, $\text{GL}_2(\mathbb{R})/\text{SL}_2(\mathbb{R}) \cong \mathbb{R}^\times$ by the first isomorphism theorem.
5. The sign function $\text{sign}: \mathbb{R}^\times \rightarrow \{\pm 1\}$ sending each nonzero real number x to its sign is a homomorphism that is surjective with kernel $\{x \in \mathbb{R}^\times : x > 0\} = \mathbb{R}_{>0}$, so $\mathbb{R}^\times/\mathbb{R}_{>0} \cong \{\pm 1\}$.

Nonexamples

1. From Example 6 in Section 9, the subgroups H and N of S_4 are both isomorphic to \mathbb{Z}_2^2 but H is not normal in S_4 while N is normal in S_4 .
2. For odd primes p , the Heisenberg group

$$\text{Heis}(\mathbb{Z}_p) = \left\{ \begin{pmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{pmatrix} : a, b, c \in \mathbb{Z}_p \right\}$$

is a non-abelian group of order p^3 in which all non-identity elements have order p . The group \mathbb{Z}_p^3 is an abelian group of order p^3 in which all non-identity elements have order p . Thus $\text{Heis}(\mathbb{Z}_p)$ and \mathbb{Z}_p^3 have the same number of element of each order, but they are not isomorphic (one group is abelian and the other is not.)

3. The simplest reason two finite groups would not be isomorphic is that they don't have the same size. For prime p we will describe two finite groups of the same order built from $\text{GL}_2(\mathbb{Z}_p)$, one a subgroup and the other a quotient group. Then we will determine whether or not the two groups are isomorphic.

Subgroup of $\text{GL}_2(\mathbb{Z}_p)$. The first group is $\text{SL}_2(\mathbb{Z}_p)$. The determinant $\det: \text{GL}_2(\mathbb{Z}_p) \rightarrow U(p)$ is a homomorphism that is surjective (same proof as for real matrices) with kernel $\text{SL}_2(\mathbb{Z}_p)$, so $\text{GL}_2(\mathbb{Z}_p)/\text{SL}_2(\mathbb{Z}_p) \cong U(p)$ by the first isomorphism theorem. Thus $|\text{GL}_2(\mathbb{Z}_p)|/|\text{SL}_2(\mathbb{Z}_p)| = |U(p)| = p - 1$, so $|\text{SL}_2(\mathbb{Z}_p)| = |\text{GL}_2(\mathbb{Z}_p)|/(p - 1)$.

Quotient group of $\text{GL}_2(\mathbb{Z}_p)$. The second group is $\text{GL}_2(\mathbb{Z}_p)/Z$, where Z is the center of $\text{GL}_2(\mathbb{Z}_p)$. The center is the scalar diagonal matrices $\begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} = aI_2$ for nonzero a in \mathbb{Z}_p : such matrices are in the center, and conversely a matrix that commutes with $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ and $\begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$ is already scalar diagonal. Thus $|Z| = |\{aI_2 : a \in U(p)\}| = p - 1$. The center is a normal subgroup and the quotient group $\text{GL}_2(\mathbb{Z}_p)/Z$ has order $|\text{GL}_2(\mathbb{Z}_p)|/(p - 1)$, which matches the order of $\text{SL}_2(\mathbb{Z}_p)$: even though we have not listed here exactly what the order *is*, we found the same formula for the order of $\text{SL}_2(\mathbb{Z}_p)$ and $\text{GL}_2(\mathbb{Z}_p)/Z$.

Are these two groups isomorphic? To prove they are, we'd like to write down an isomorphism between them. To prove they are not isomorphic, we need to find some group-theoretic property that they do not share. Which way does it go?

For odd primes p we will show $\text{SL}_2(\mathbb{Z}_p)$ has a nontrivial center while $\text{GL}_2(\mathbb{Z}_p)/Z$ has a trivial center, so they are *not* isomorphic.

That $\text{SL}_2(\mathbb{Z}_p)$ has a nontrivial center can be shown with an explicit example: $-I_2 = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$ is in $\text{SL}_2(\mathbb{Z}_p)$ and it's not the identity since $-1 \neq 1$ in \mathbb{Z}_p (here is where we use $p \neq 2$). Since it is a scalar diagonal matrix, it commutes with all matrices in $\text{SL}_2(\mathbb{Z}_p)$.

To show $\text{GL}_2(\mathbb{Z}_p)/Z$ is trivial, suppose in this group that $\overline{\begin{pmatrix} a & b \\ c & d \end{pmatrix}}$ lies in its center. That means $\overline{\begin{pmatrix} a & b \\ c & d \end{pmatrix}} \overline{A} = \overline{A} \overline{\begin{pmatrix} a & b \\ c & d \end{pmatrix}}$ for all $\overline{A} \in \text{GL}_2(\mathbb{Z}_p)/Z$. We want to deduce that $\overline{\begin{pmatrix} a & b \\ c & d \end{pmatrix}}$ is trivial in $\text{GL}_2(\mathbb{Z}_p)/Z$.

The condition $\overline{\begin{pmatrix} a & b \\ c & d \end{pmatrix}} \overline{A} = \overline{A} \overline{\begin{pmatrix} a & b \\ c & d \end{pmatrix}}$ means $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ and A commute “modulo Z ”, which for $A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ and $A = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$ says

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x & 0 \\ 0 & x \end{pmatrix}$$

and

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} y & 0 \\ 0 & y \end{pmatrix}$$

for some nonzero x and y in \mathbb{Z}_p . These equations simplify to

$$\begin{pmatrix} a & a+b \\ c & c+d \end{pmatrix} = \begin{pmatrix} x(a+c) & x(b+d) \\ xc & xd \end{pmatrix}, \quad \begin{pmatrix} a+b & b \\ c+d & d \end{pmatrix} = \begin{pmatrix} ay & by \\ (a+c)y & (b+d)y \end{pmatrix}$$

in $\text{GL}_2(\mathbb{Z}_p)$.

From the second row of the first equation we get $c = xc$ and $c+d = xd$. If $x \neq 1$ then $c = 0$ by the first equation, so the second equation becomes $d = xd$, so $d = 0$. But an invertible matrix can't have 2nd row $(0 \ 0)$, so $x \neq 1$. Arguing similarly with the second column of the second equation we get $b = by$ and $d = (b+d)y$; if $y \neq 1$ then $b = 0$, so $d = dy$, so $d = 0$, making the second column $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$, which is impossible. Thus $x = 1$ and $y = 1$, which makes the above equations

$$\begin{pmatrix} a & a+b \\ c & c+d \end{pmatrix} = \begin{pmatrix} a+c & b+d \\ c & d \end{pmatrix}, \quad \begin{pmatrix} a+b & b \\ c+d & d \end{pmatrix} = \begin{pmatrix} a & b \\ a+c & b+d \end{pmatrix}.$$

From the first equation, $c = 0$ and $a = d$ in \mathbb{Z}_p . From the second equation, $b = 0$ and $a = d$ again. So $\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix}$, which is in Z , so our original matrix is trivial in $\text{GL}_2(\mathbb{Z}_p)/Z$. That completes the proof that $\text{GL}_2(\mathbb{Z}_p)/Z$ has a trivial center.

12 Direct products

Definitions and Theorems

1. **Theorem.** Let G_1, G_2 be groups and let

$$G = G_1 \times G_2 = \{(g_1, g_2) : g_1 \in G_1 \text{ and } g_2 \in G_2\}.$$

Define a binary operation on G by

$$(a_1, a_2)(b_1, b_2) = (a_1b_1, a_2b_2).$$

Then G is a group with respect to this operation. The identity is (e_1, e_2) and the inverse of (g_1, g_2) is (g_1^{-1}, g_2^{-1}) .

2. The group $G = G_1 \times G_2$ in the previous theorem is called the (*external*) *direct product* of G_1 and G_2 . This is a kind of “multiplication” of two groups. We start with G_1 and G_2 , and build $G_1 \times G_2$. Inside $G_1 \times G_2$ are subgroups $G_1 \times \{e_2\}$ and $\{e_1\} \times G_2$, which are isomorphic to G_1 and G_2 , respectively. Even if G_1 or G_2 is nonabelian, in $G_1 \times G_2$ the elements of G_1 commute with the elements of G_2 : $(g_1, g_2) = (g_1, e_2)(e_1, g_2) = (e_1, g_2)(g_1, e_2)$.
3. The definition of direct products can be extended to more than two groups by induction, and $\prod_{i=1}^n G_i$ is used as a shorthand for $G_1 \times G_2 \times \cdots \times G_n$. If $G_1 = G_2 = \cdots = G_n = G$, then it is common to write G^n for $\underbrace{G \times \cdots \times G}_{n \text{ times}}$.
4. **Theorem** Let $(g, h) \in G \times H$. If g and h have finite orders m and n respectively, then the order of (g, h) in $G \times H$ is the least common multiple of m and n .
5. **Theorem** The group $\mathbb{Z}_m \times \mathbb{Z}_n$ is isomorphic to \mathbb{Z}_{mn} if and only if $\gcd(m, n) = 1$.
6. **Theorem.** For groups G_1 and G_2 , $G_1 \times G_2$ is abelian if and only if G_1 and G_2 are both abelian.
7. **Theorem.** If G_1 and G_2 are finite cyclic groups with relatively prime order then $G_1 \times G_2$ is cyclic. (The converse is false, e.g., $\mathbb{Z}_2 \times \mathbb{Z}_2$ has order 4 and no element has order 4.)
8. Reversing the construction of direct products (passing from “multiplication” to “factoring”), when is a group isomorphic to a direct product of two subgroups? Let G be a group with subgroups H and K satisfying the following conditions.

- $G = HK = \{hk : h \in H, k \in K\}$
- $H \cap K = \{e\}$
- $hk = kh$ for all $k \in K$ and $h \in H$.

Then $G \cong H \times K$, where an isomorphism $f: H \times K \rightarrow G$ is given by $f(h, k) = hk$. We say G is the (*internal*) *direct product* of its subgroups H and K .

Examples

- $\mathbb{R}^n = \underbrace{\mathbb{R} \times \cdots \times \mathbb{R}}_{n \text{ times}}$ is a direct product of n copies of \mathbb{R} .
- $\mathbb{Z}_2 \times \mathbb{Z}_2$ and $\mathbb{Z}_2 \times \mathbb{Z}_4$ are direct products of abelian groups that are not cyclic: the first has order 4 but each element has order 1 or 2, while the second has order 8 and each element has order dividing 4.
- $\mathbb{Z}_2 \times \mathbb{Z}_3$ is cyclic: $(1, 1)$ is a generator.
- $\mathbb{R}^\times \cong \{\pm 1\} \times \mathbb{R}_{>0}$ since each nonzero real number has a unique expression in the form $\pm x$ for some sign and some $x > 0$. This is an example of an internal direct product with $H = \{\pm 1\}$ and $K = \mathbb{R}_{>0}$.

Nonexamples

- In the group D_n we have subgroups $H = \langle r \rangle = \{1, r, r^2, \dots, r^{n-1}\}$ and $K = \langle s \rangle = \{1, s\}$ with $D_n = HK$ (each element of D_n is of the form r^i or $r^i s$ for some exponent i) and $H \cap K = \{1\}$, but that does *not* mean $D_n \cong H \times K$. Indeed, $H \times K = \langle r \rangle \times \langle s \rangle$ is abelian since H and K are both abelian, but D_n is nonabelian. What goes “wrong” here is that elements of D_n written in the form r^i or $r^i s$ do not multiply componentwise, *e.g.*, $(1s)(rs) \neq rs^2 = r$. In fact, $(1s)(rs) = r^{-1}ss = r^{n-1}$, which is not r . (More generally, $(r^i s)(r^j s) = r^{i-j}$, which is not usually $r^i r^j s^2 = r^{i+j}$.)